

EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	1	10/550107	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:17
L2	1	Karabassi near Evaggelia- Aggeliki near Penteli	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:18
L3	2	Karanastasis near Nikolaos	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:23
L4	2	Voliotis near Konstantinos	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:23
L5	2	((2 or 3) or 4)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:23
L6	12337	calibrat\$3 near6 object	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:24
L7	5138	calibrat\$3 near2 object	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:24
L8	1066	L7 and (camera sensor) and laser	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:24
L9	821	L8 and dimension\$4	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:24

L10	2691	calibrat\$3 near object	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:24
L11	596	L10 and (camera sensor) and laser	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:24
L12	451	L11 and dimension\$4	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:24
L13	365	L12 and angle	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:24
L14	111	L12 and view\$3 near5 angle	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:24
L15	32	L14 and calibrat\$3 near3 pattern\$3	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:25
L16	2691	calibrat\$3 near object	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:25
L17	338	L16 and calibrat\$3 near2 camera	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:25
L18	96	L17 and calibrat\$3 near3 pattern\$3	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:25
L19	12	L18 and laser near4 camera	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:25

L20	2691	calibrat\$3 near object	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:25
L21	338	L20 and calibrat\$3 near2 camera	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:25
L22	96	L21 and calibrat\$3 near3 pattern\$3	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:25
L23	12	L22 and laser near4 camera	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:25
L24	2691	calibrat\$3 near object	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:25
L25	596	L24 and (camera sensor) and laser	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:25
L26	451	L25 and dimension\$4	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:25
L27	111	L26 and view\$3 near5 angle	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:25
L28	32	L27 and calibrat\$3 near3 pattern\$3	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:25
L29	13	L28 and @pd< "20041007"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:26

L30	31	calibrat\$3 near2 object and calibrat\$3 near2 (camera and laser)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:26
L31	10	L30 and @pd<"20041007"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:26
L32	34	calibrat\$3 near object and two near plane\$3 and angles and (camera and laser)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:26
L33	8	calibrat\$3 near object and two near plane\$3 and angles and (camera and laser) and Tsai	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:27
L34	14	calibrat\$3 near object and two near plane\$3 and angles and visible and Tsai	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:27
L35	11	calibrat\$3 near object and two near plane\$3 and position\$3 and orientat\$3 and Tsai	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:27
L36	9	calibrat\$3 near object and (two near plane\$3) near9 angle\$3 and orientat\$3	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:27
L37	1	calibrat\$3 near object and (two near plane\$3) near9 angle\$3 and Tsai	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:27
L38	19	27 and "356"/\$.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:29
L39	7	27 and "250"/\$.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:29

L40	36	27 and "382"/\$.ocls.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:29
L41	22	27 and "345"/\$.ocls.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:29
L42	0	27 and "700"/\$.ocls.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:29
L43	5	27 and "702"/\$.ocls.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:30
L44	69	(((((38 or 39) or 40) or 41) or 42) or 43)	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:30
L45	36	44 and @pd<"20041007"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:30
L46	1	(calibrat\$3 and camera and laser and (calibrat\$3 near4 object) and distance and angle and dimension\$3 and plane\$2 and pattern\$2 and (position location) and tsai and visible and space). clm.	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2009/03/24 20:40

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